



Active Exploration Mechanisms in Autonomous Learning and Development A Robotic Modeling Perspective

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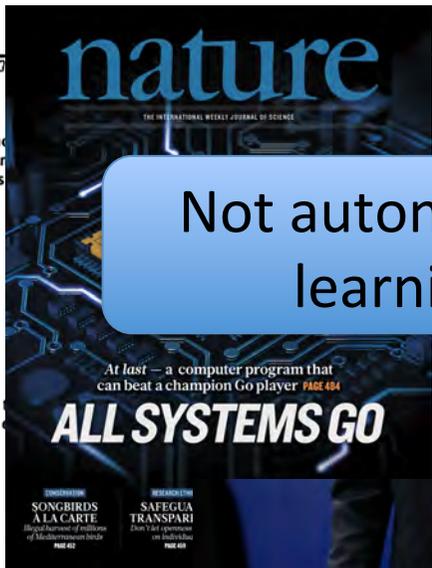


European
Research
Council



Autonomous Learning and Development in Human Infants

PHYSICAL DEVELOPMENT	Average age skills begin	3 months	6 months	9 months	1 year	5 years
Head and trunk control	lifts head part way up	holds head up briefly holds head up high and well	holds up head and shoulders	turns head and shifts weight	holds head up well when lifted moves and holds head easily in all directions	
Rolling		rolls belly to back	rolls back to belly	rolls over and over easily in play		
Sitting		sits only with full support sits with some support	sits with hand support	begins to sit without support	sits well without support	
Crawling and walking		begins to creep	scoots or crawls	pulls to standing	takes steps	
Arm and hand control	grips finger put into hand	begins to reach towards objects	reaches and grasps with whole hand	passes object from one hand to other	grasps with thumb and forefinger	



Not autonomous learning



- How do developmental structures form?
- What is the role of structured learning curriculums?
- How do they enable autonomous learning?

Team: ~20-25 people

- 4 Inria seniors:
PY. Oudeyer, M. Lopes,
D. Roy, A-L. Vollmer
- 3 Ensta ParisTech
seniors:
D. Filliat, F. Stulp,
A. Gepperth
- 8-9 PhDs
- 3-5 engineers
- 1-3 postdocs



Cognitive sciences
models to understand better
human development

Many collaborations with
researchers in

- Developmental psychology
- Neuroscience
- Robotics and AI
- Educational sciences

Lifelong autonomous
learning in
robotics and AI

Applications in
educational technologies



Exploration and guidance mechanisms

Intrinsic motivation, active learning curiosity

- Cognitive science
- Robotics/AI
- Applications in education

Body morphology and growth

- Cognitive science
- Robotics/AI
- Applications in education

Interactive learning, imitation

- Cognitive science
- Robotics/AI
- Applications in education

Exploration and guidance mechanisms

Intrinsic motivation, active learning curiosity

- Cognitive science 
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Interactive learning, imitation

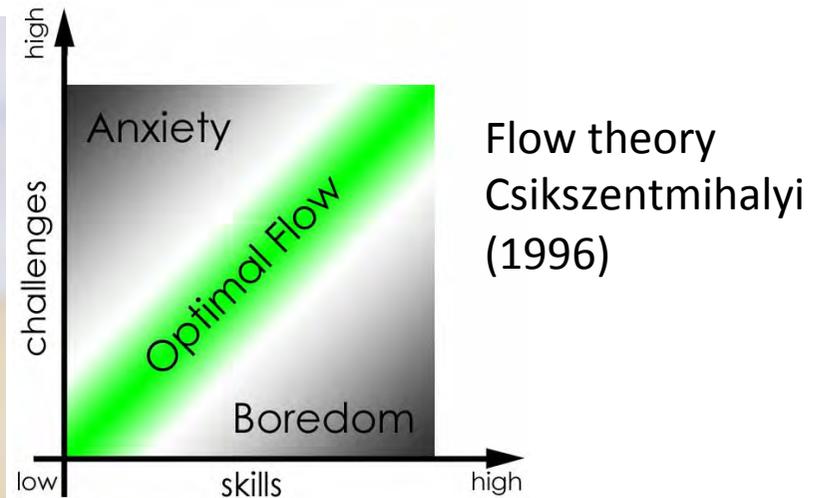
- Cognitive science
- Robotics/AI
- Applications in education

Spontaneous active exploration



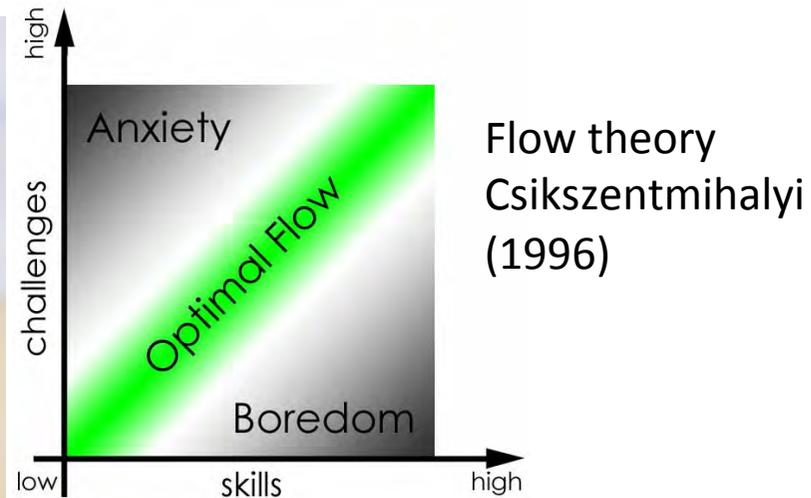
<https://www.youtube.com/watch?v=8vNxjw2AqY>

Intrinsic motivation, curiosity and active learning



- ➔ Intrinsic drive to reduce uncertainty, and to experiencing novelty, surprise, cognitive dissonance, challenge, incongruences, ...
- ➔ Optimal interest = optimal difficulty = neither trivial nor too difficult challenges
Berlyne (1960), White (1960), Kagan (1972), Csikszentmihalyi (1996), (Kidd et al., 2012), ...
See review in (Oudeyer et al., 2016)

Intrinsic motivation, curiosity and active learning

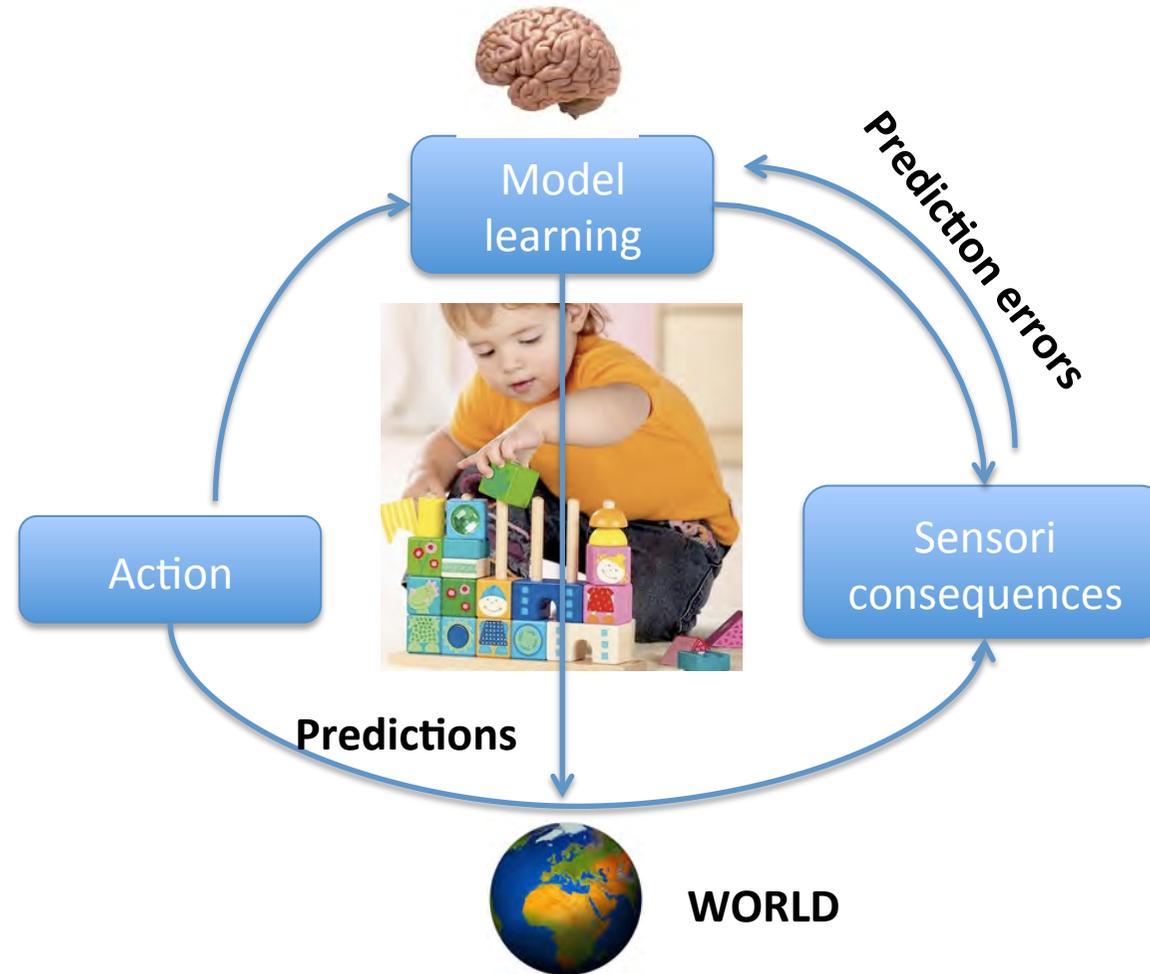


➔ Intrinsic drive to reduce uncertainty, and to experiencing novelty, surprise, cognitive dissonance, challenge

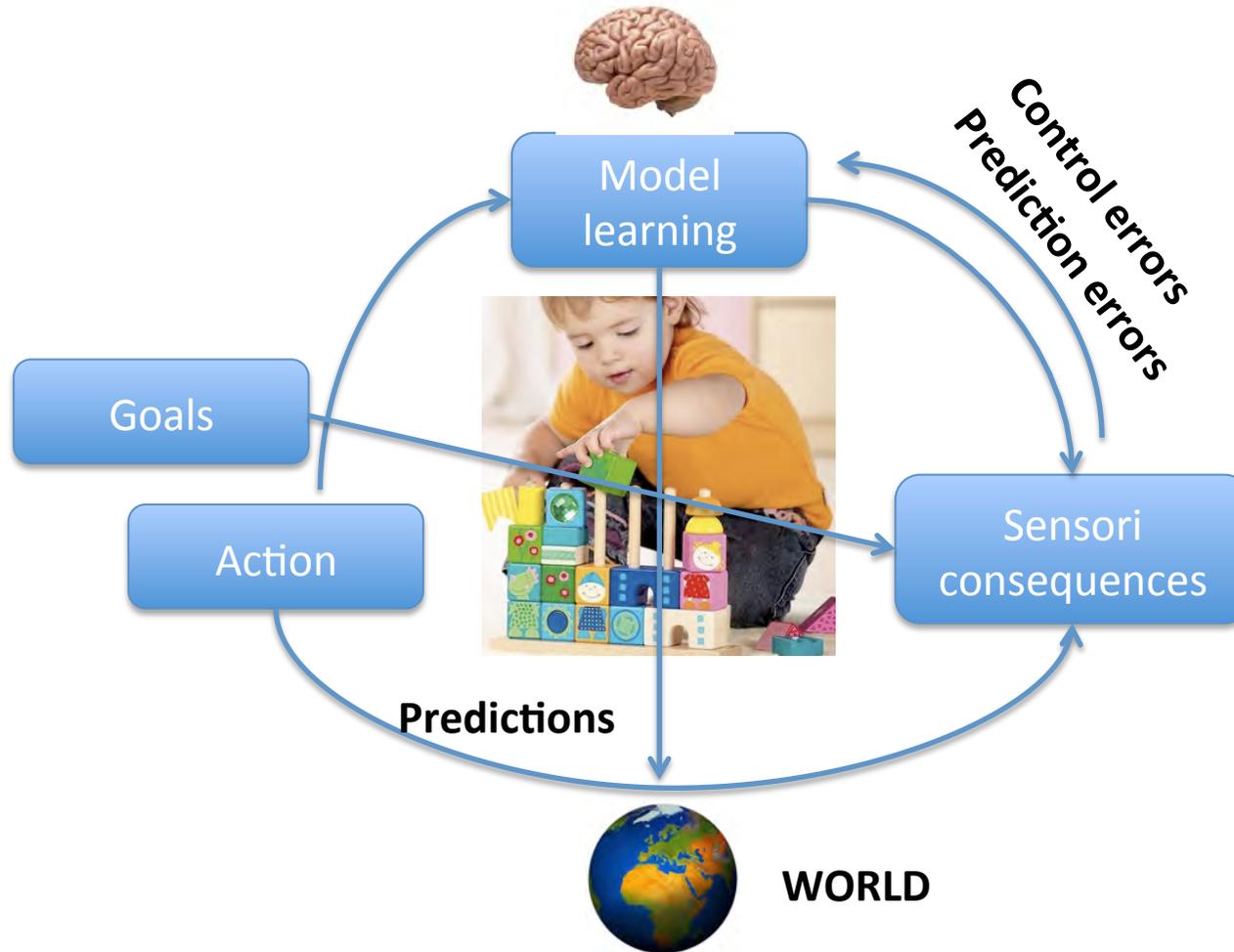
Contribution of Flowers lab and colleagues in the last 10 years:
Development of a **unified formal and theoretical framework**
in psychology and neuroscience

(Frontiers in Neuroscience 2007; IEEE TEC 2007; Trends in Cognitive Science, Nov. 2013; Progress in Brain Research, 2016; Frontiers in Neuroscience, 2014; Scientific Reports, 2016; PNAS, in press)

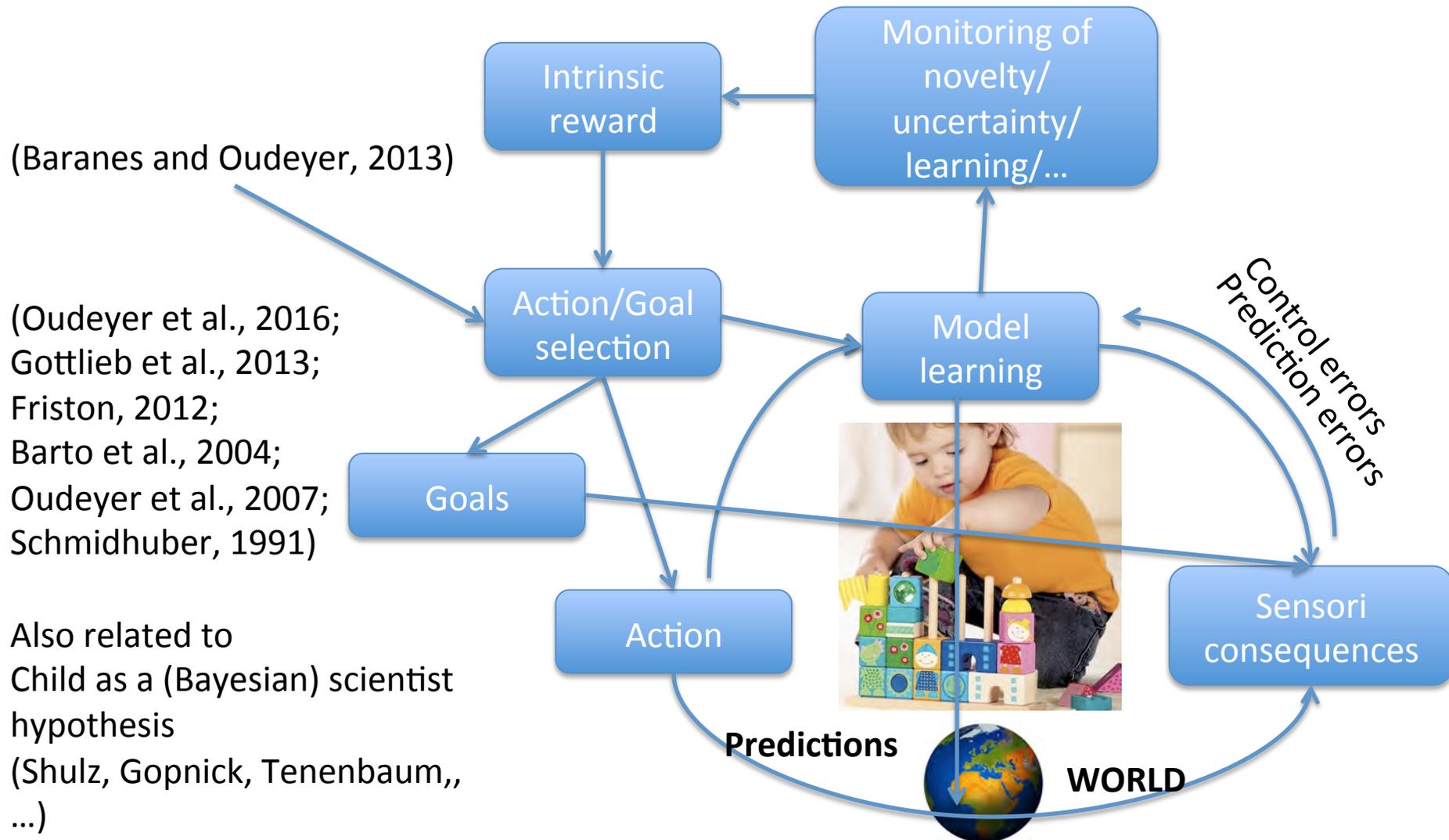
Predictive brain framework: Exploring to learn world models



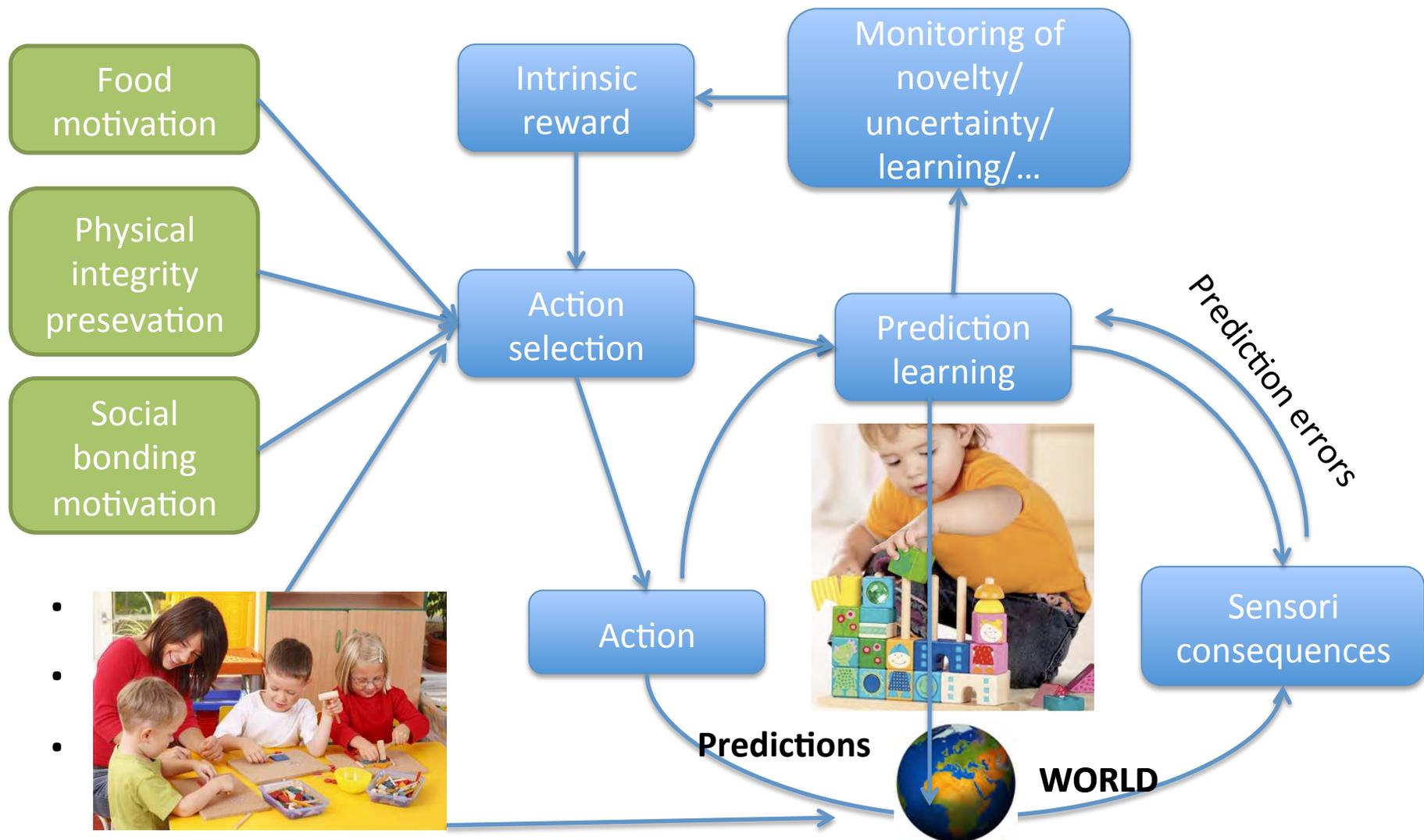
Predictive brain framework: Exploring to learn world models



The active exploration system

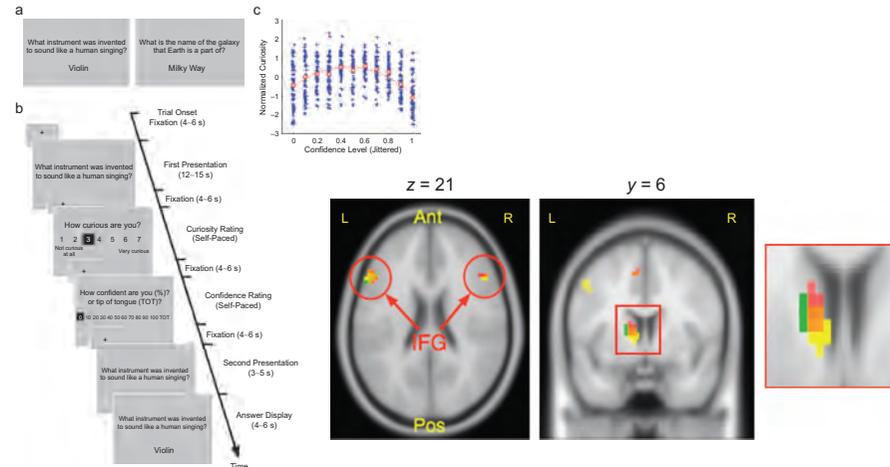


Interaction with other motivations and learning mechanism



Curiosity in experimental studies

Attention driven by surprising external stimuli
in short time scales



- Perceptual curiosity e.g. Stahl and Feigenson, 2015
- Epistemic curiosity e.g. Kang et al., 2009; Gruber et al., 2014
- Study impact on memorization/learning
- Neural correlates (also in monkeys, e.g. Waelti et al., 2001; Gottlieb et al., 2013)
- Behavioral correlates (e.g. eye movements, Baranes et al., 2015)

Spontaneous exploration:

Beyond visual attention towards
external stimuli,

Beyond surprise,

Beyond short-time scales:

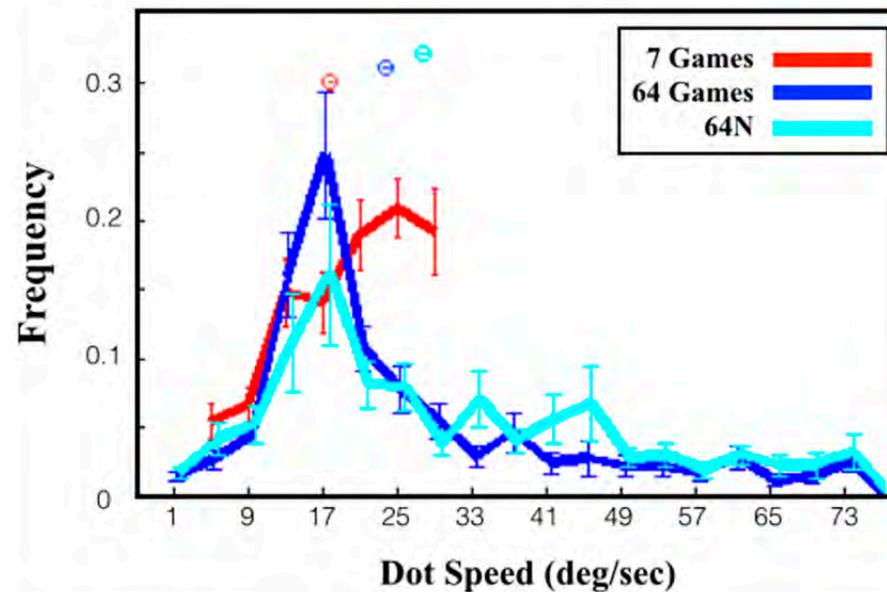
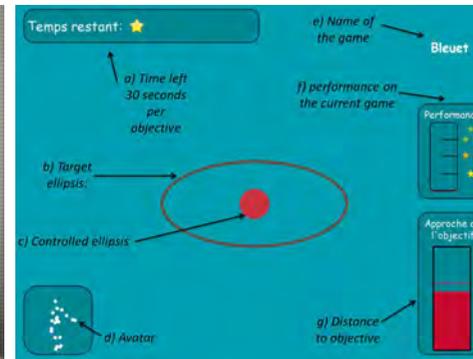
Open questions

in psychology and neuroscience

(1) Beyond visual attention towards external stimuli

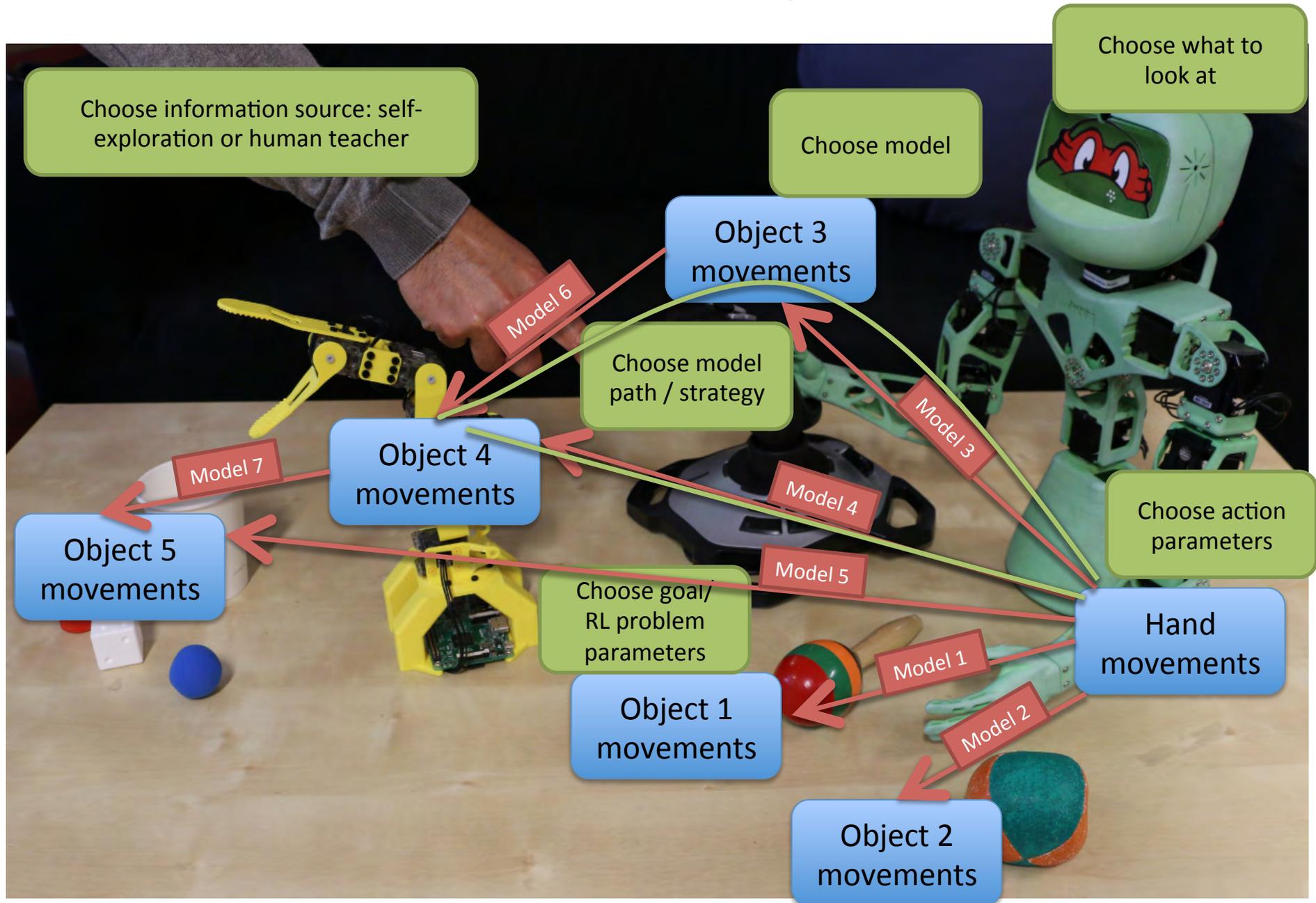
➔ *What kind of choices can be made during active exploration?
(interestingness of what?)*

Intrinsically motivated exploration of sensorimotor activities



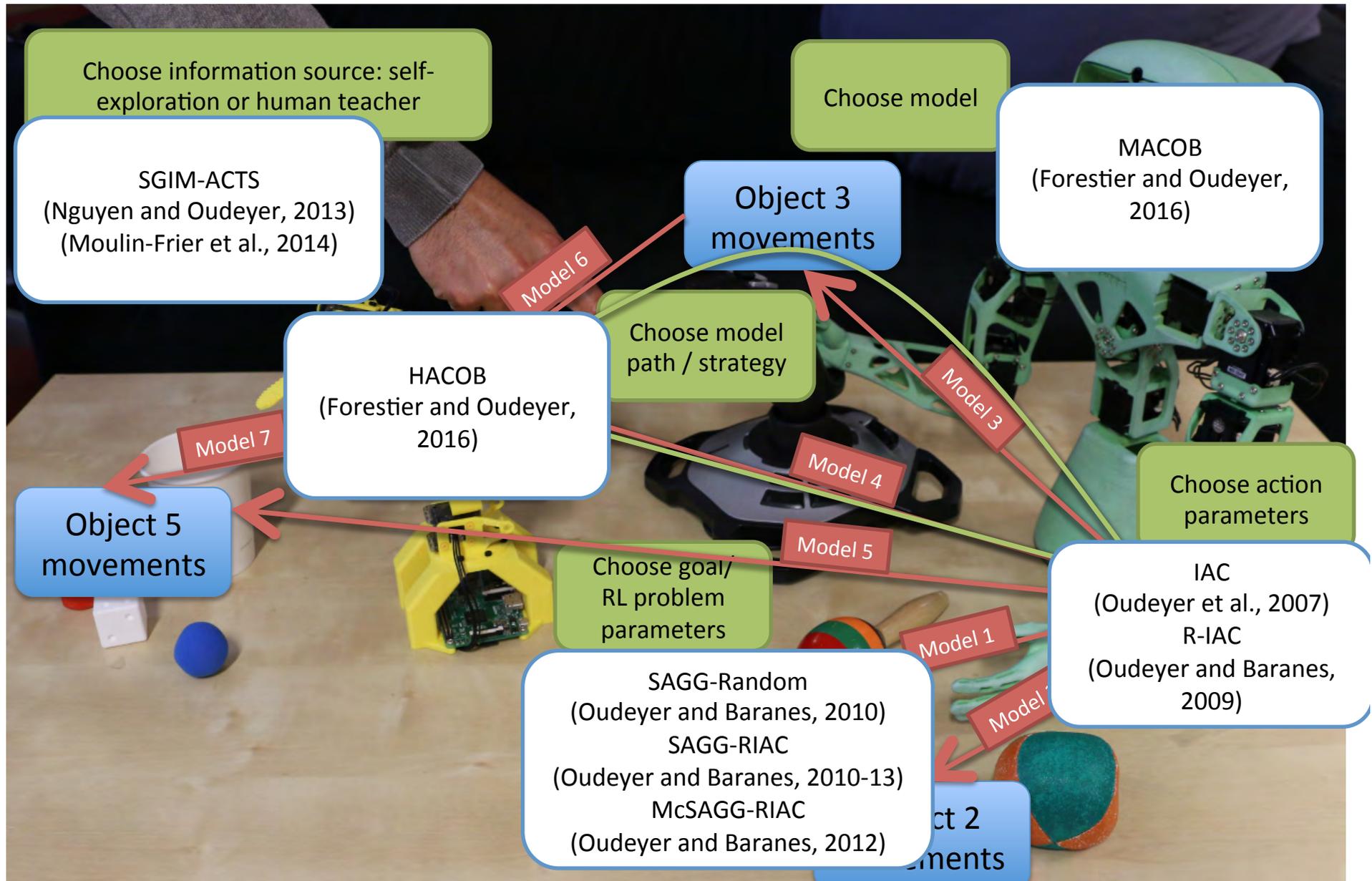
(Frontiers in Neuroscience, 2014; ICDL-Epirob 2014;
See also Scientific Reports, 2016; PNAS, in press)

The choice spaces in curiosity-driven exploration



Hierarchical strategic learning algorithms

(Lopes and Oudeyer, 2012; Nguyen and Oudeyer, 2013)



(1) Beyond « surprise »: *what are the features of interestingness?*

- High novelty/high complexity?
- (Bayesian ?) Surprise? (Itti and Baldi)
- Knowledge gap, cognitive dissonance? (Kagan, Festinger, Lowenstein)
- Intermediate novelty, intermediate complexity? (Berlyne, Kidd)
- Intermediate challenge? (White, Csikszentmihalyi)
- Free energy? (Friston)
- **Learning progress, improvement of prediction errors? (Oudeyer et al., Schmidhuber)**



All these measures can be mathematically modelled and compared in computational and robotic experiments
(Oudeyer, Gottlieb and Lopes, 2016)

What is intrinsic motivation? A typology of computational approaches

Pierre-Yves Oudeyer^{1,2,*} and Frederic Kaplan³

					Homeostatic (-) vs Heterostatic (+)	Motivation	Exploration potential	Organization potential	Computational cost	Existing models	
Internal	Intrinsic	Adaptive	Knowledge-based	Information theoretic	+	UM	***	*	***	**	
						IGM	***	***	***	**	
						DSM	**	***	***	*	
				Predictive	-	DFM	*	***	***	*	
						+	NM	***	*	*	***
							ILNM	**	**	*	**
		Competence-based	+	LPM	***	***	**	**			
				SM	**	**	**	*			
				FM	*	***	**	**			
			-	IM	***	*	**	*			
				CPM	***	***	**	*			
				CM	*	***	**	*			
	Fixed	Morphological	-	SyncM	*	***	**	**			
				StabM	*	***	*	**			
			+	VarM	***	*	*	*			
				Extrinsic		-	SocM	/	/	*	***
Extrinsic		-	EnerM	/	/	*	***				

Figure 7. This table presents all the models discussed in this paper and the families to which they belong. For each model we give a rough estimation of its exploration potential (how likely such a motivation can lead to exploratory and investigation behaviours) and of its organization potential (how likely such a motivation can lead to a structured and organized behaviour). We also estimate the computational cost and number of computational models existing so far for each of the categories.

Active curiosity-driven exploration as a means to learn models of the world dynamics/affordances?

- ➔ Searching for maximal novelty or uncertainty or entropy will not be efficient at all!



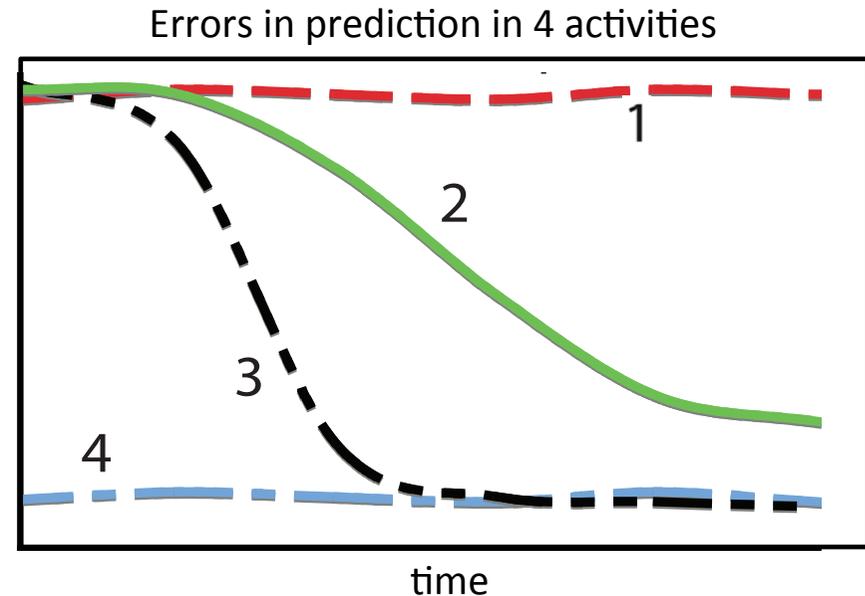
The Learning Progress hypothesis

→ Explore tasks that currently maximize empirical learning progress

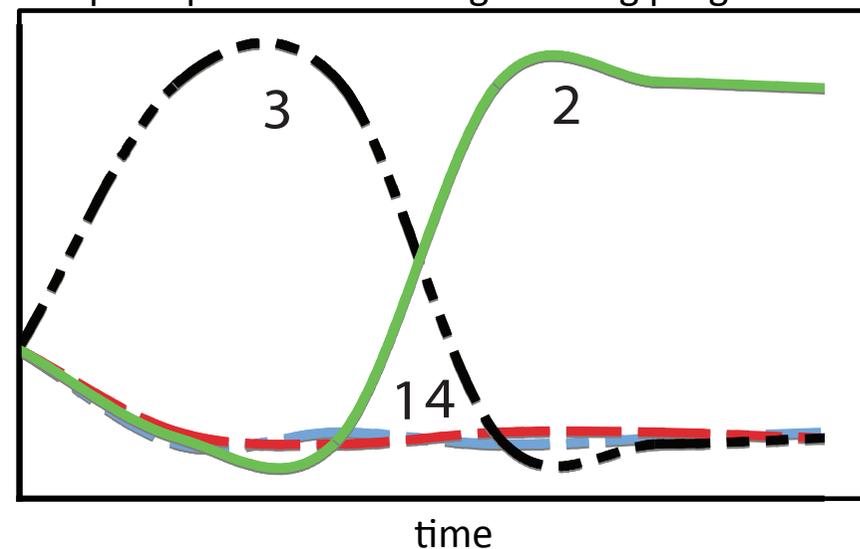
(Oudeyer et al., 2004; 2007; Gottlieb et al., 2013; Oudeyer et al., 2016)

→ Optimal active learning of multiple tasks with concave learning curves in the Strategic Student Learning framework (Lopes and Oudeyer, 2012)

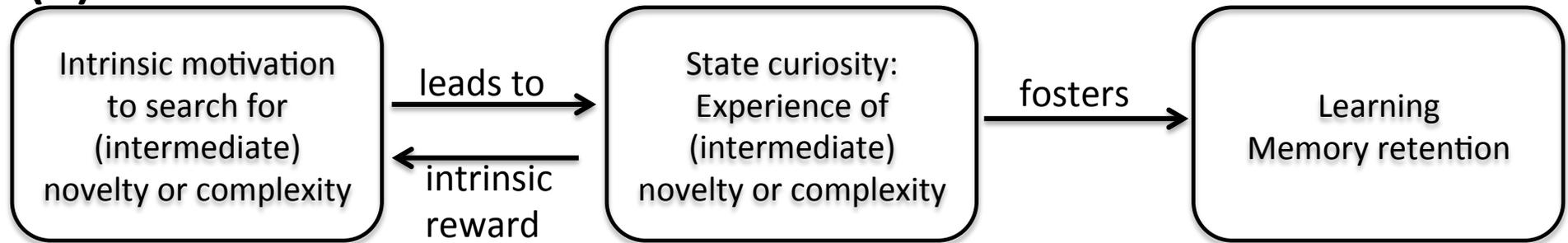
→ This achieves automated and intrinsically motivated curriculum learning of multiple tasks and/or models (Oudeyer et al., 2007; Oudeyer and Baranes, 2013; Forestier et al., 2016)



% of time spent in each activity based on the principle of maximizing learning progress

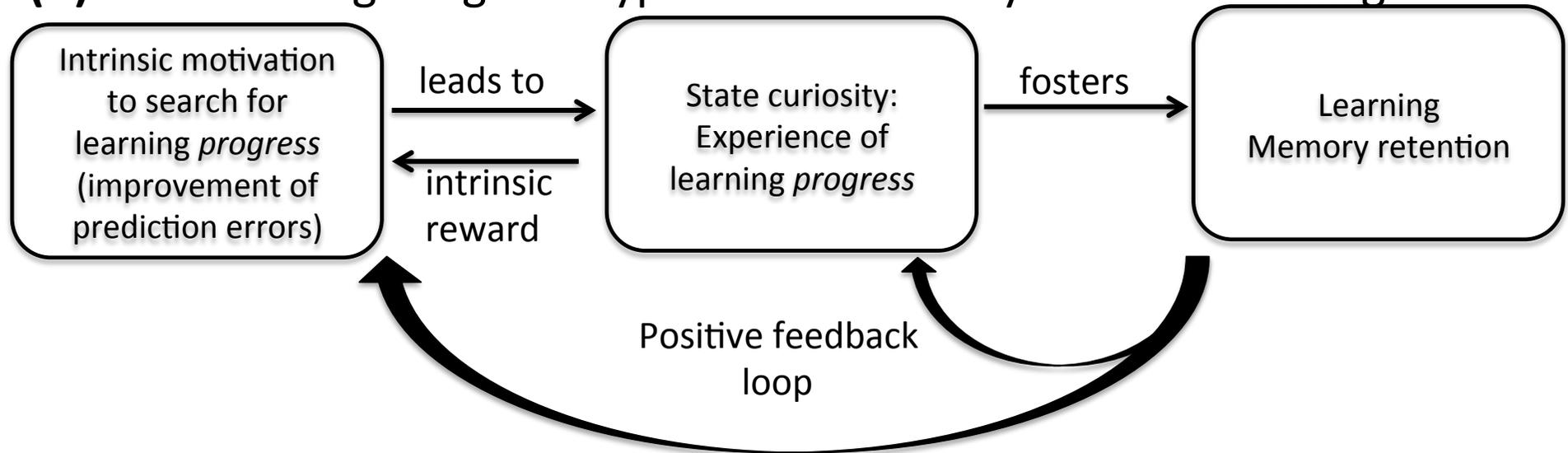


(A)



(Walti et al., 2001; Kang et al., 2009; Gruber et al., 2014; Stahl and Feigenson, 2015)

(B) The Learning Progress hypothesis: curiosity = active learning

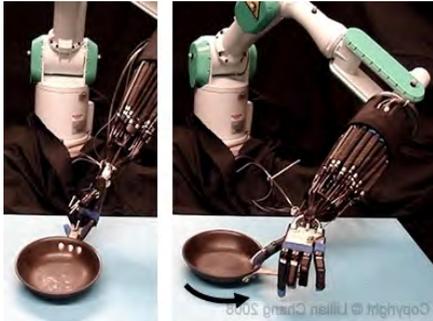


(Oudeyer et al., 2007; Oudeyer, Gottlieb, Lopes, 2016)

Examples of model architectures

Curiosity-driven active Motor Exploration

(active selection of parameterized motor programs)



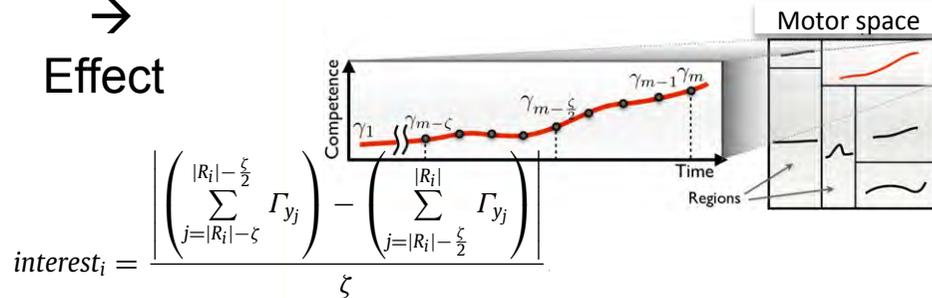
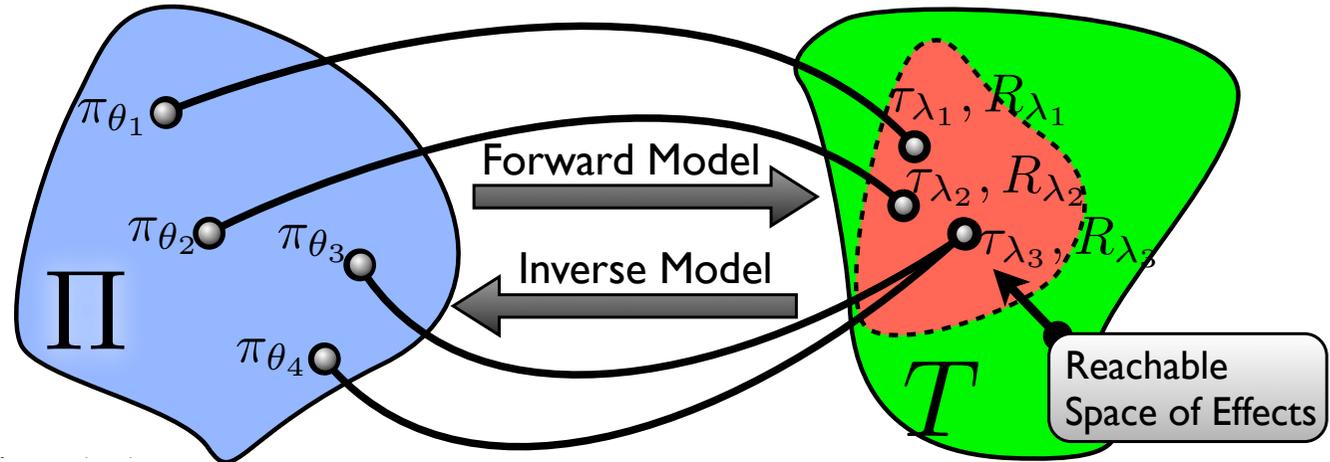
(Context, Movement)



Effect

Space of Controllers

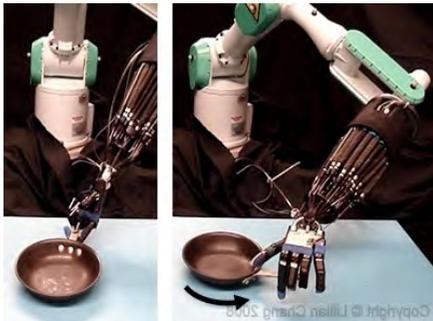
Task Space = Space of Effects



Cost function for driving motor exploration = generating dynamically a learning curriculum

Curiosity-driven active Goal Exploration

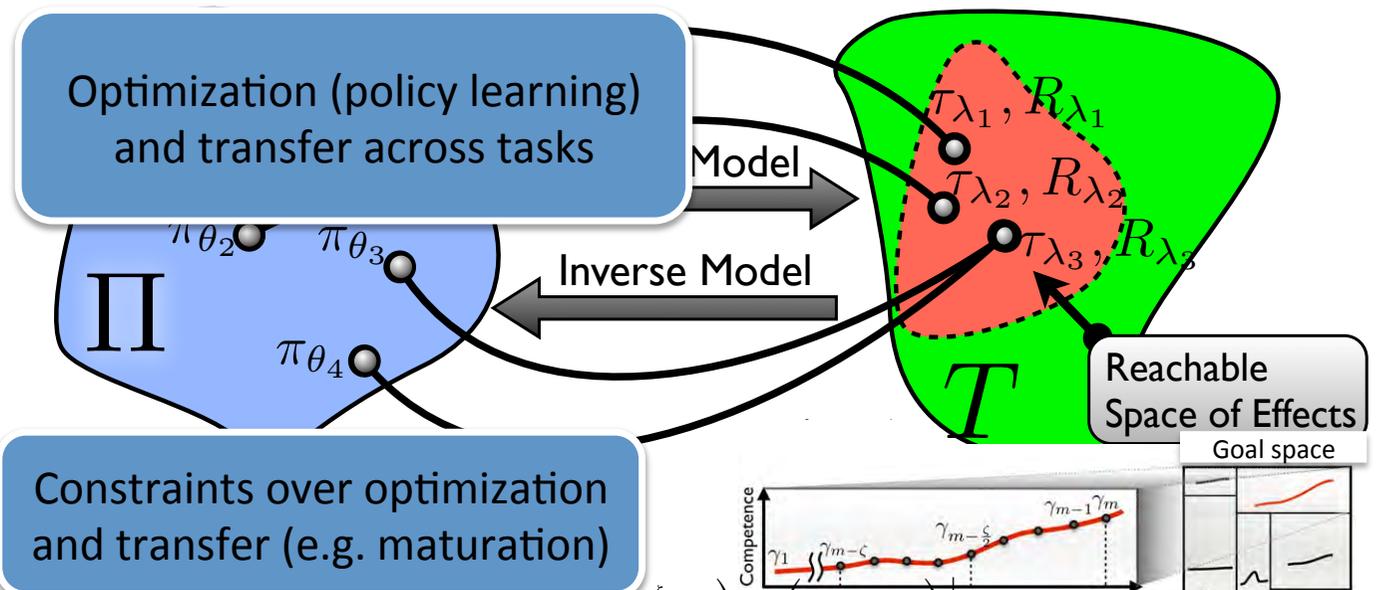
(active selection of parameterized RL problems)



(Context, Movement)
→
Effect

Space of Controllers

Task Space = Space of Effects



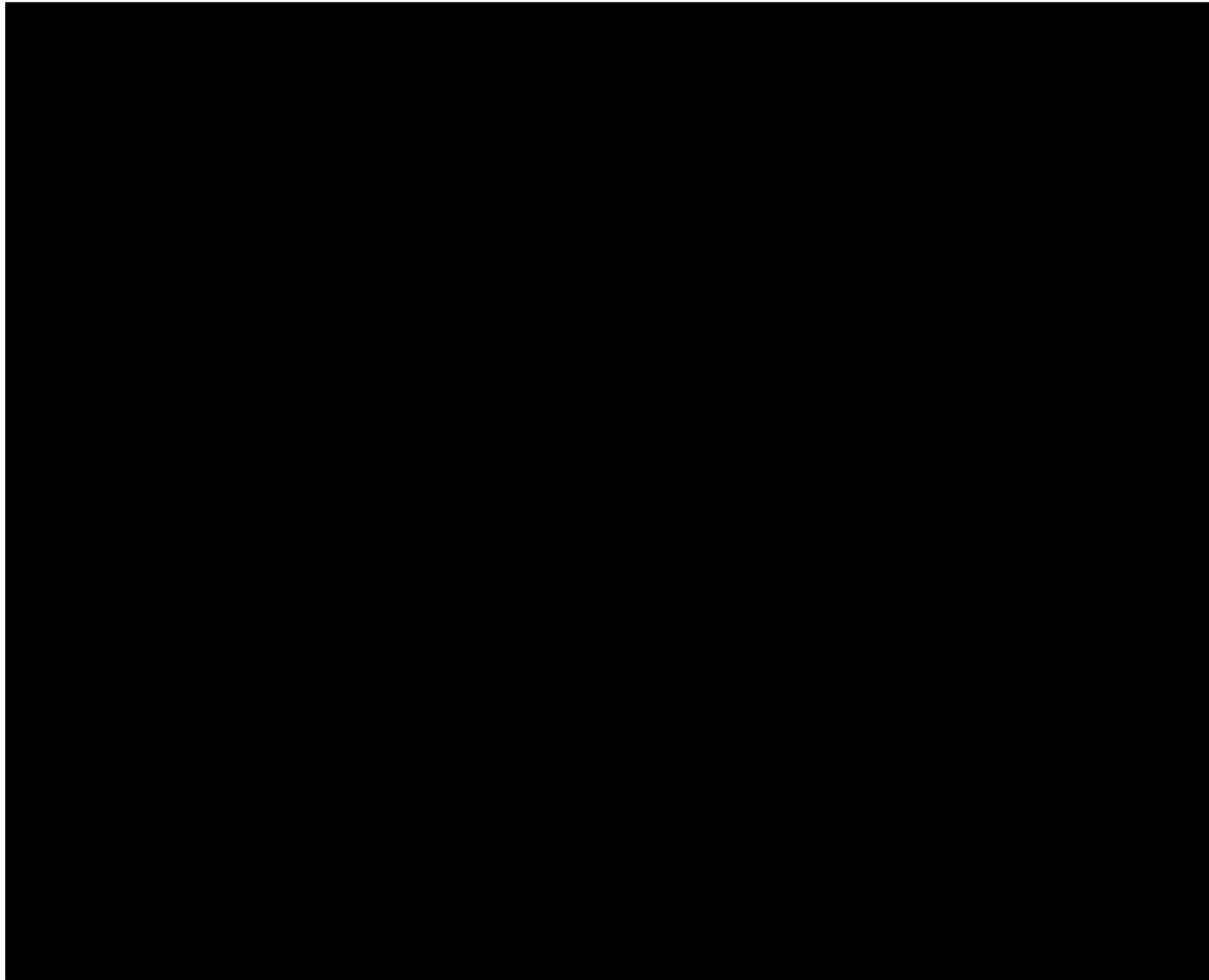
$$interest_i = \frac{\left(\sum_{j=|R_i|-\xi}^{|R_i|-\frac{\xi}{2}} \Gamma_{y_j} \right) - \left(\sum_{j=|R_i|-\frac{\xi}{2}}^{|R_i|} \Gamma_{y_j} \right)}{r}$$

Cost function for driving multi-task exploration = generating dynamically a learning curriculum

(5) Do short-term curiosity-driven exploration mechanisms have consequences on **long term organization of learning?**

(= how intrinsic motivation can self-organize curriculum learning?)

The Playground Experiments



(Oudeyer et al., IEEE Trans. EC 2007; Oudeyer and Smith, 2016)

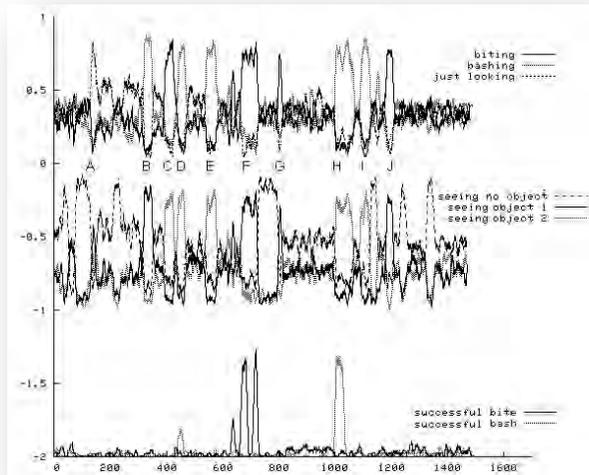
<https://www.youtube.com/watch?v=uAoNzHjzys>

Autonomous acquisition of skill repertoires



Functions:

- Autonomous learning of novel affordances and skills, e.g. object manipulation, before they are needed for external needs
 - Self-organization of developmental trajectories, bootstrapping of communication
- ➔ Developmental and evolutionary consequences



TOPICS

TOPICS IN COGNITIVE SCIENCE



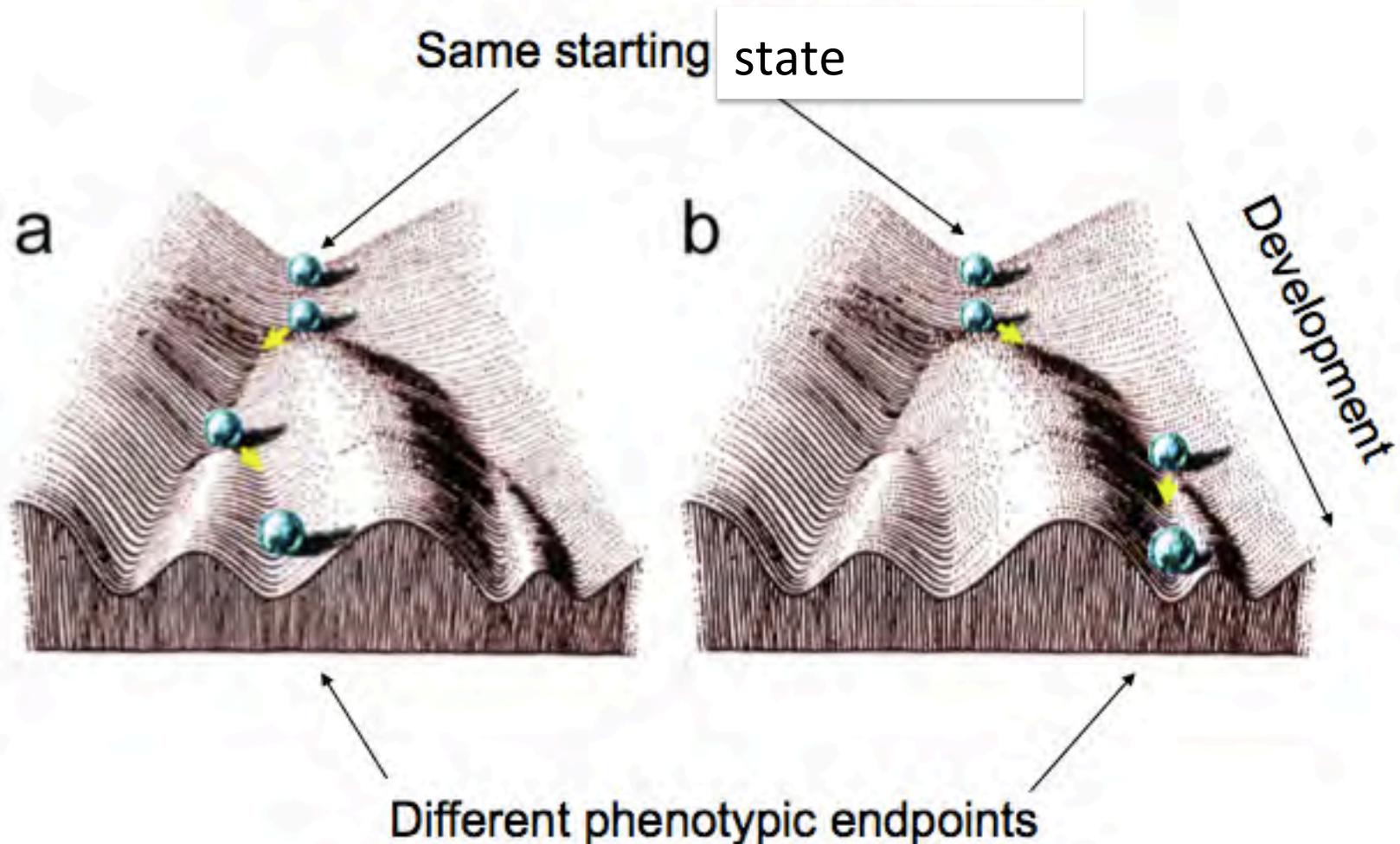
Topics in Cognitive Science (2016) 1–11
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ISSN:1756-8757 print/1756-8765 online
DOI: 10.1111/tops.12196

How Evolution May Work Through Curiosity-Driven Developmental Process

Pierre-Yves Oudeyer,^a Linda B. Smith^b

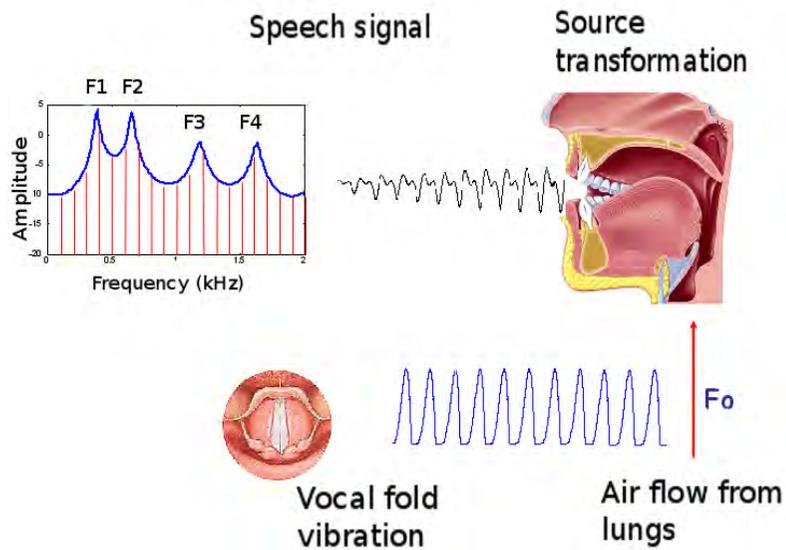
Regularities and diversity in developmental trajectories

Intrinsic developmental variation



(after Waddington's epigenetic landscape)

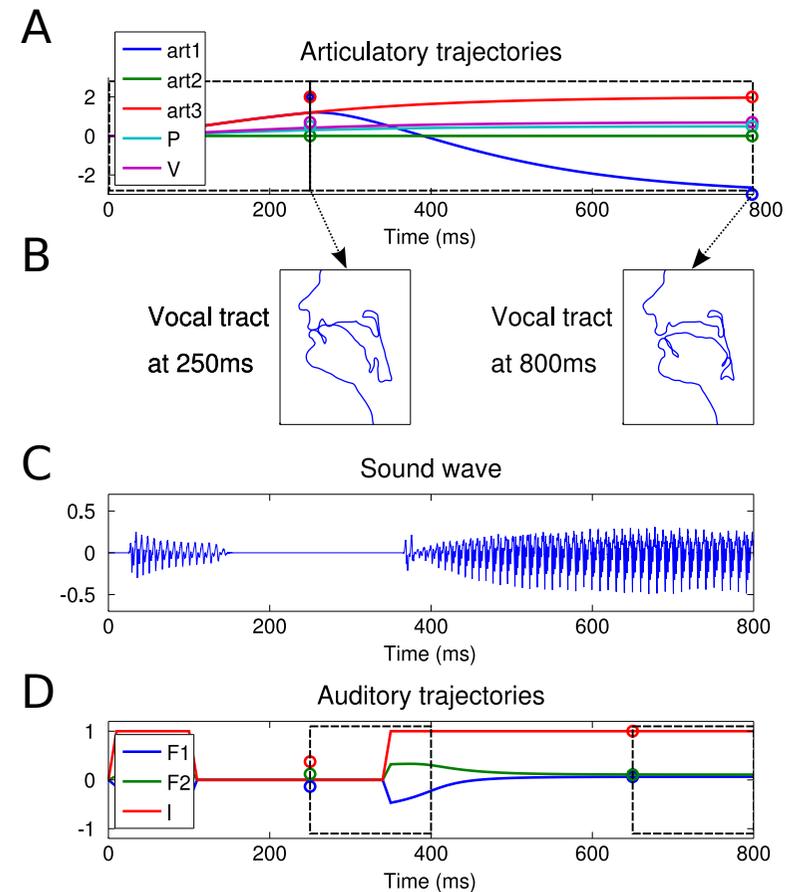
Self-organization of vocal development



DIVA Vocal tract model (Guenther)

Two-layers active learning:

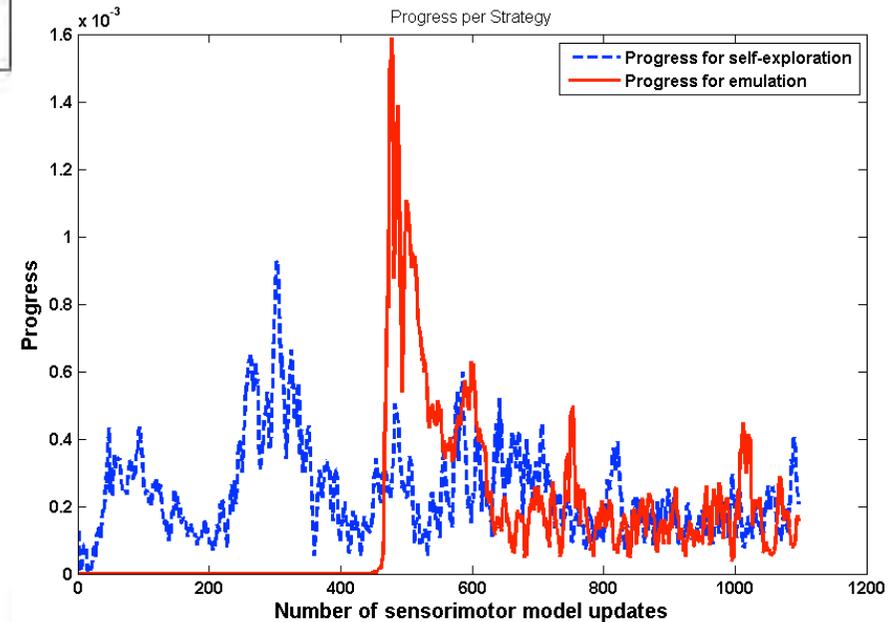
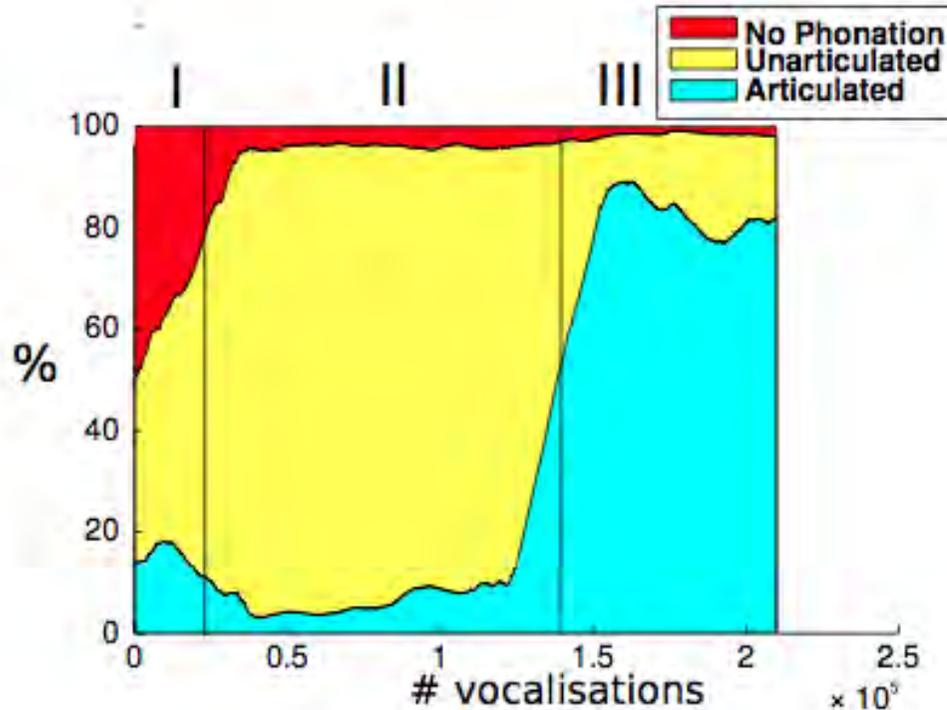
- 1) Active choice self-exploration vs. Imitation
- 2) If self-exploration: active goal selection



- Collaboration with D. K. Oller, Univ. Memphis, US

(Moulin-Frier, Nguyen and Oudeyer, *Frontiers in Cognitive Science*, 2013)

Emergent developmental stages



0-3 mo:
squeals, growls,
yelps ...

3-7 mo:
quasi-vowels

7-10 mo:
language-independent
proto-syllables

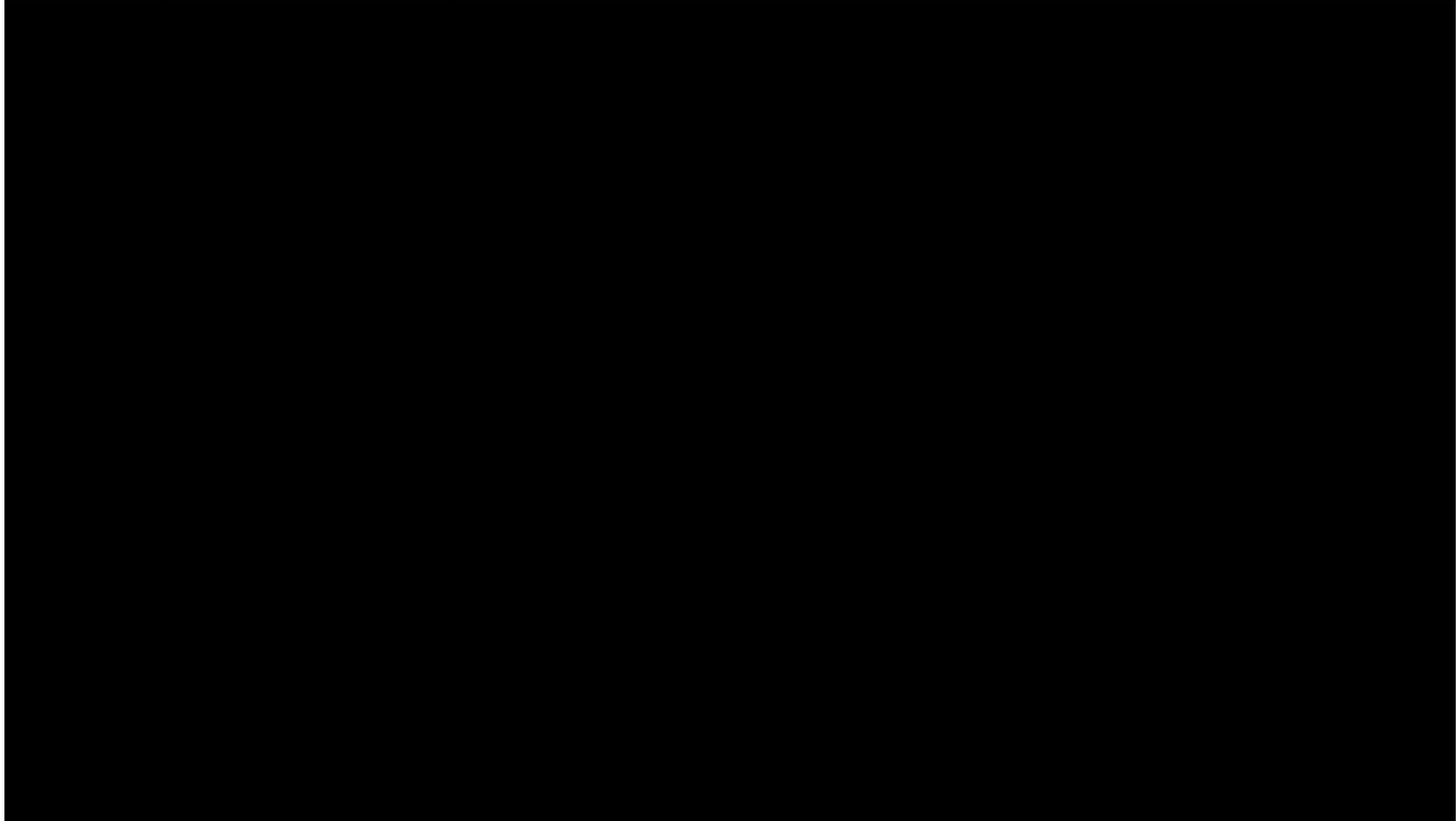
10 mo:
influence by
ambient language

12 mo:
first words

Approximate age

(Oller, 2000)

Learning tool use (nested affordances)
+ using intrinsic motivation to learn
complex RL problem with rare rewards



<https://www.youtube.com/watch?v=NOLAwD4ZTW0>

Nested tool use, 2nd Best demo prize @NIPS, 2016³³
(in front of several GAFAs demos)₃₃

Reinterpreting infant tool use experiments?

→ e.g. Chen and Siegler on strategy selection
(see Forestier and Oudeyer, CogSci 2016; ICDL-Epirob 2016)

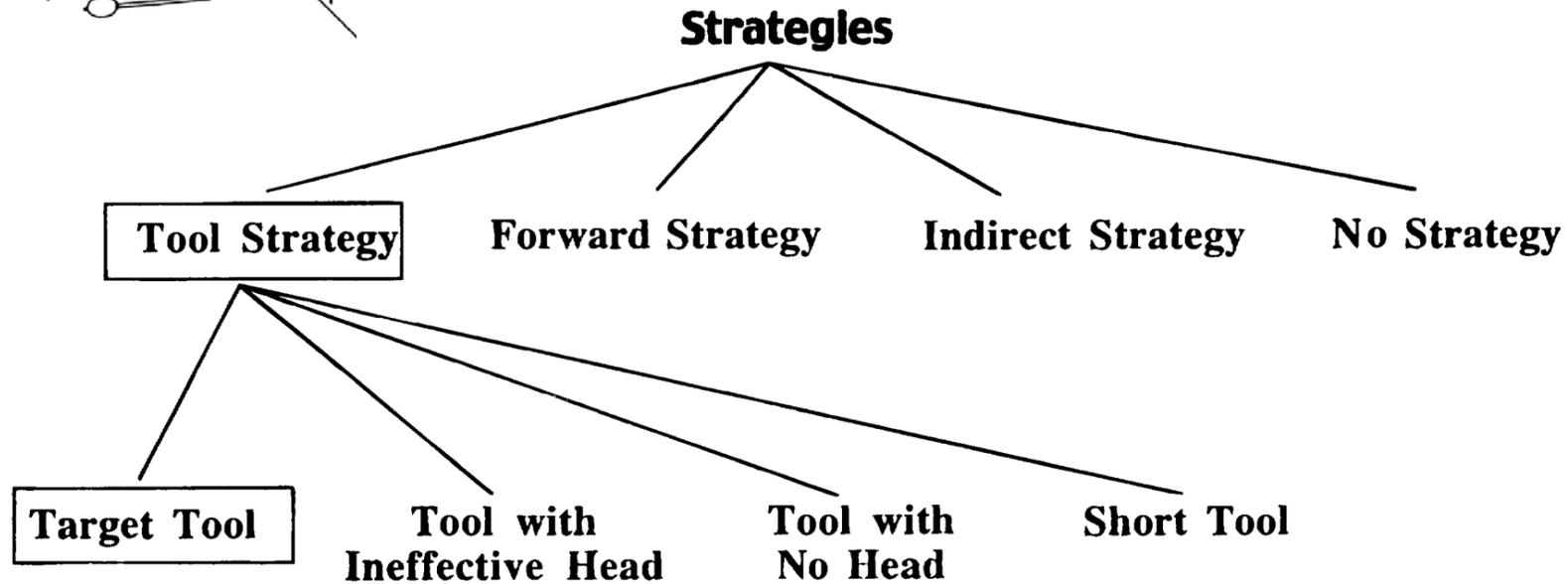
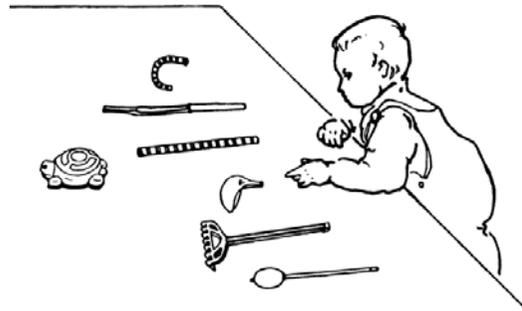
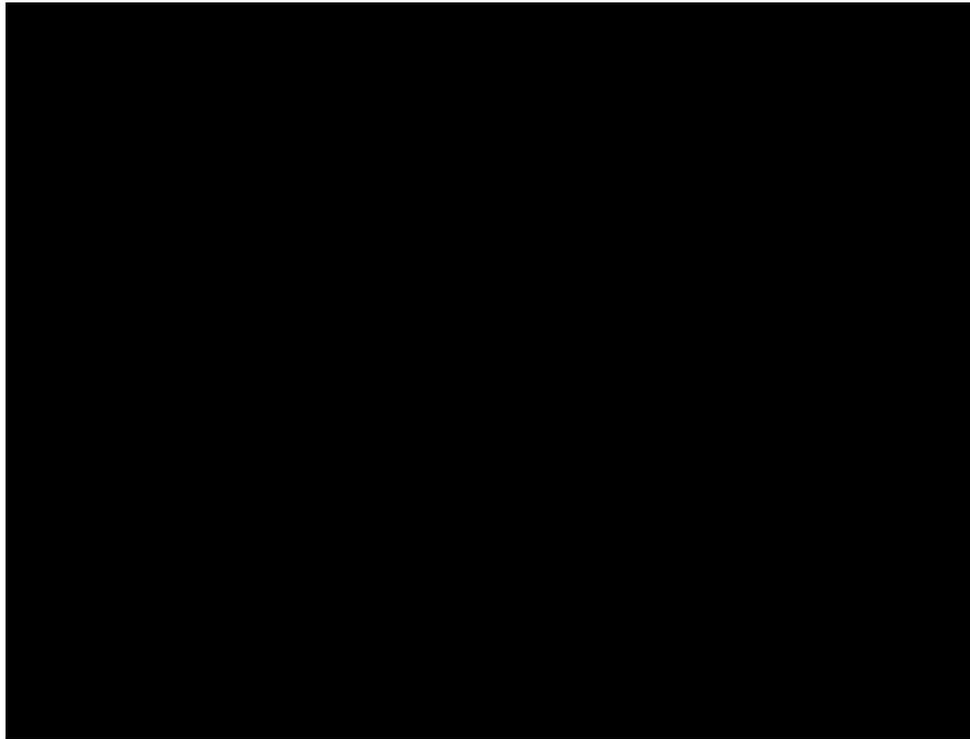


FIGURE 3.—The hierarchy of strategies among which children needed to choose.

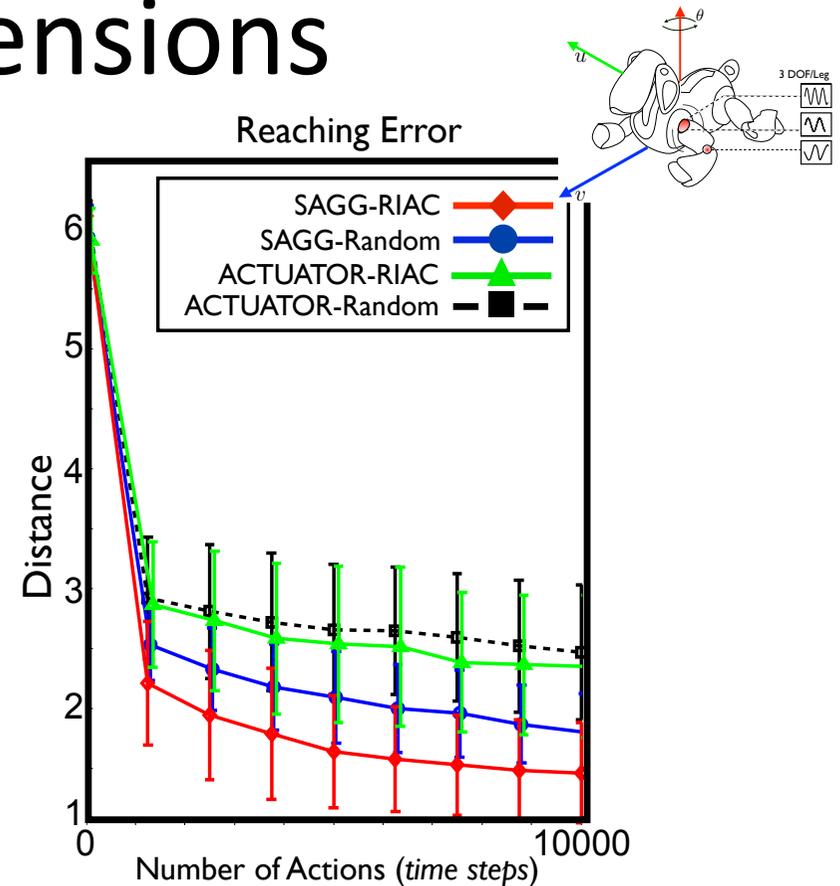
Efficiency of LP-based curiosity-driven learning of skills

Efficiency of active learning in high-dimensions

Active learning of omnidirectional locomotion



Control Space: $[-1;1]^{24}$ Task Space: $[-1;1]^3$



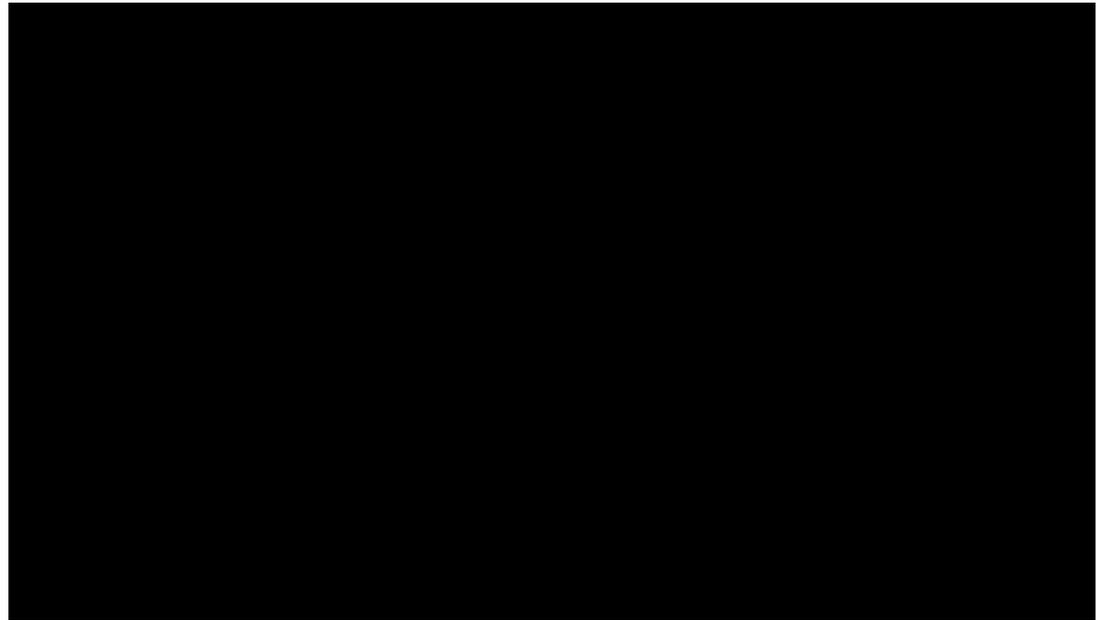
https://www.youtube.com/watch?v=_HusNBLV7yM

➔ Performance higher than more classical active learning algorithms in real sensorimotor spaces (non-stationary, non homogeneous)

(Baranes and Oudeyer, IEEE TAMD 2009; Robotics and Autonomous Systems; 2013)

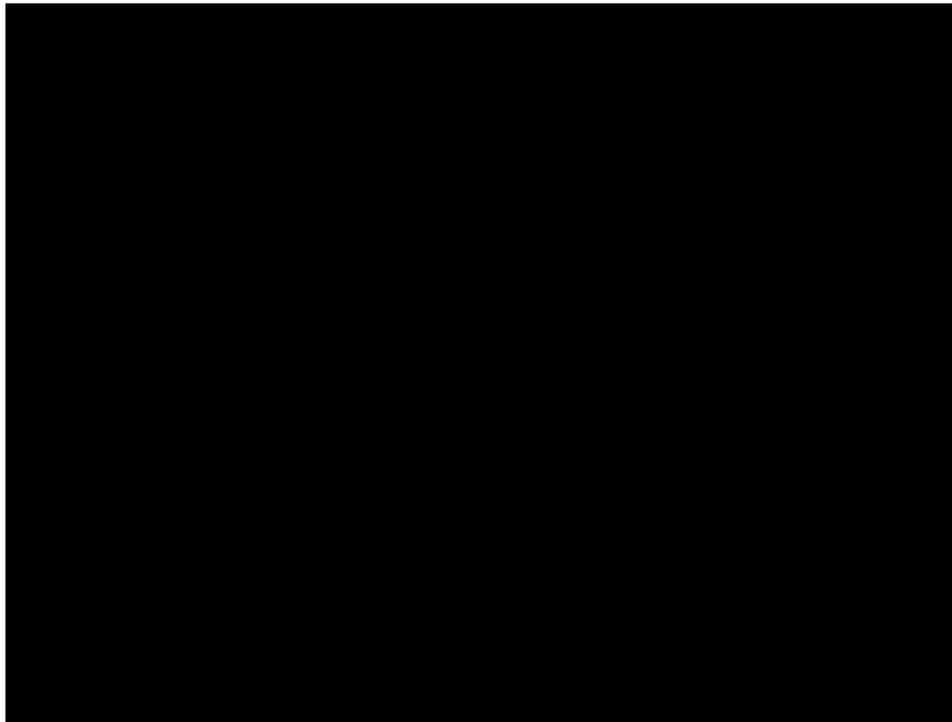
Learning omnidirectional control of
soft/deformable objects
(Autonomous Robots, 2014)

Active scheduling of both tasks and learning
strategies by active selection of when to ask
help to human teachers, which teacher to ask,
and what to ask them
(Paladyn journal of Behavioural Robotics, 2013)



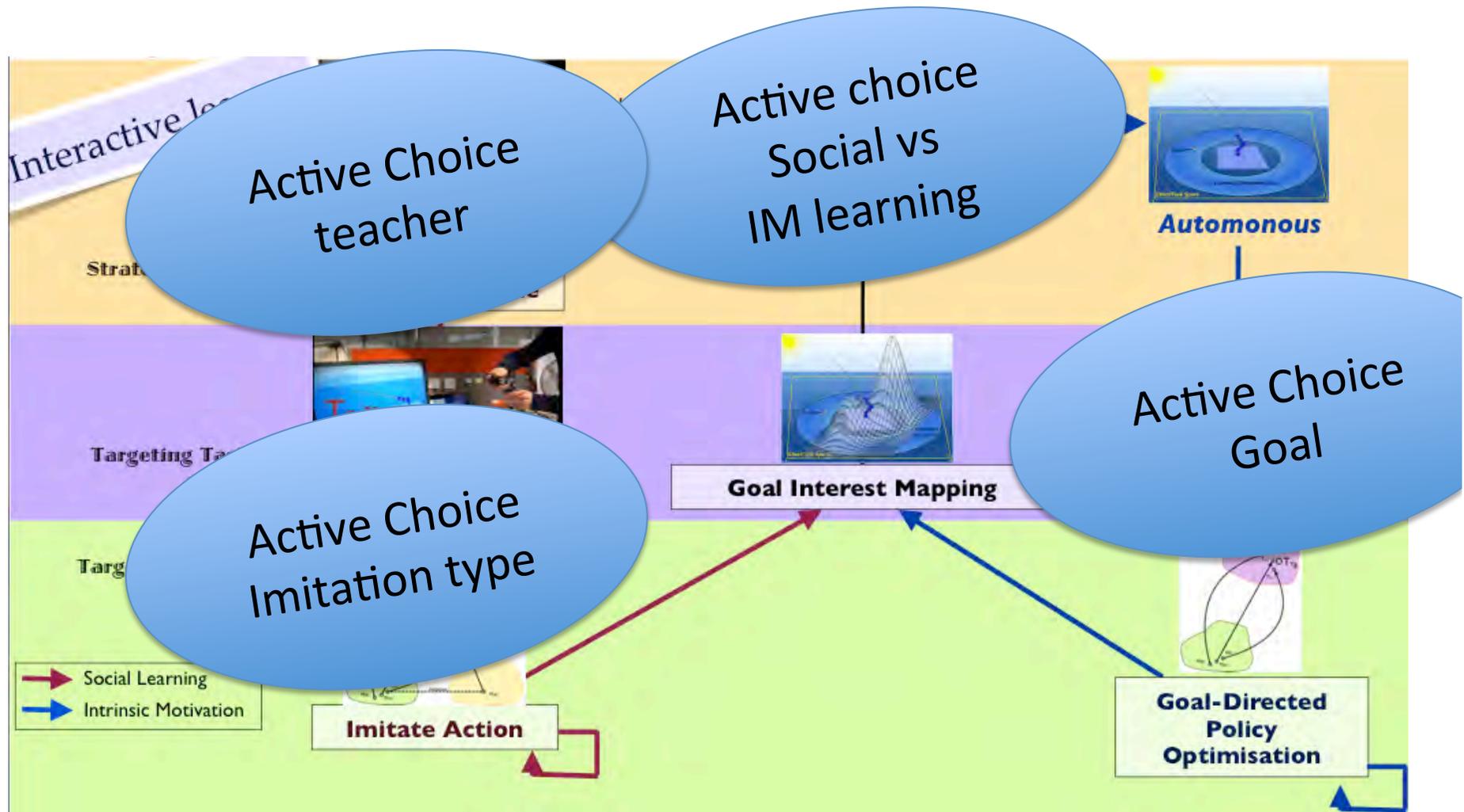
<https://www.youtube.com/watch?v=OWjLaGv33i0>

<https://www.youtube.com/watch?v=m-desi46Uwk>



Perceptual/visual representations
(IEEE TAMd, 2014; ICRA 2016; IROS 2016)

Curiosity-driven active choice of teachers and modes of imitation



(Nguyen and Oudeyer, Palad. Behav. Rob., 2013; Autonomous Rob. 2013)

Education tech application: automated generation of personalized learning curriculum for human brains

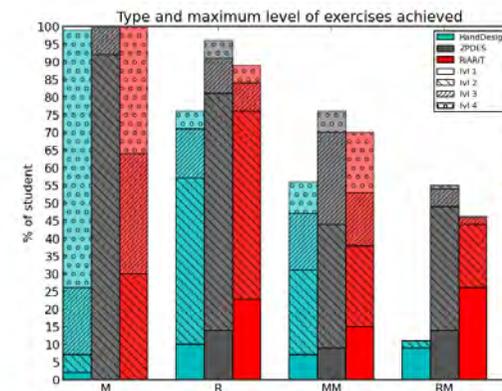


KidLearn project:

Personalization of teaching sequences
(curriculum) in Intelligent Tutoring Systems

[*\(Journal of Educational Data Mining, 2015\)*](#)

+ contract with ITWell company and transfer in Skillogs company



- 500 children in more than 10 schools
- More students reached and succeed more difficult type of exercises.

Interdisciplinary collaborations

(ERC Grant + HFSP + associate team Neurocuriosity)

Human children



Jacqueline Gottlieb,
Cognitive Neuroscience Lab
NY, US

Flowers Lab
Inria and Ensta ParisTech



Robots



Celeste Kidd
Dev. Psychology lab
Univ. Rochester



Monkeys

Linda Smith
Dev. Psych.
Indiana Univ., US



Second Interdisciplinary Symposium on Information Seeking, Curiosity and Attention (Neurocuriosity 2016)

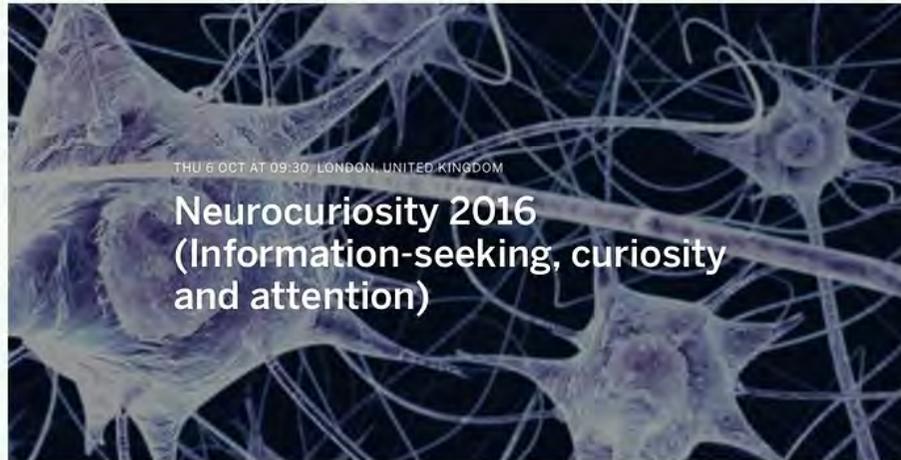
■ Curiosity in humans and animals



oudeyer

 23  May 18

First interdisciplinary symposium on Information-seeking, curiosity and attention  37



The Centre for Brain and Cognitive Development (Birkbeck) hosted the second interdisciplinary symposium on information-seeking, curiosity and attention.

Date and Location

6-8 Oct. 2016, [British Medical Association](#) , London

Programme

Click below to download a full programme with titles.

 [Neurocuriosity Programme.pdf](#)  (416.6 KB)

Thursday 6th October: 9.00am-5.45pm

Topics

The past few years have seen a surge of interest in the mechanisms of active learning, curiosity and information seeking, and this body work has highlighted a number of highly significant questions regarding higher cognition and its development (for a recent review, see [Tics13](#) ). One question is how subjects explore to build explanatory models of their environment, and how these models further constrain the sampling of additional information. A related question is how the brain generates the intrinsic motivation to seek information when physical rewards are absent or unknown, and how this impacts cognitive development in the long term.

The goal of the meeting is to foster a vigorous exchange of ideas among pre-eminent researchers who investigate these questions in neuroscience, psychology, developmental psychology, and computational modeling. The meeting will be single-track and include sessions on (1) behavior, (2) cognitive neuroscience, (3) computational modeling and (4) single neuron physiology.

Video Presentations

Organized by Inria Flowers (PY Oudeyer, M Lopes), Columbia Univ (J. Gottlieb) and Birbeck College (T. Gliga)

Neuroscience, Computational modelling, Developmental psychology, Ethology/animal research

Speakers: J. Nelson, D. Markant, S. Kouider, M. Gruber, K. Murayama, J. O'Reilly, K. Friston, G. Baldassarre, P. Dayan, K. Doya, W. Shultz, A. Bell, L. Hunt, D. Bell, K. Begus, L. Goupil, L. Feigenson, D. Bavellier, A. Gopnik.

<https://openlab-flowers.inria.fr/t/second-interdisciplinary-symposium-on-information-seeking-curiosity-and-attention-neurocuriosity-2016/187>

Selected publications

- Baranes, A., Oudeyer, P.-Y., 2013. Active learning of inverse models with intrinsically motivated goal exploration in robots. *Robot. Auton. Syst.* 61 (1), 49–73.
- Baranes, A.F., Oudeyer, P.Y., Gottlieb, J., 2014. The effects of task difficulty, novelty and the size of the search space on intrinsically motivated exploration. *Front. Neurosci.* 8, 1–9.
- Baranes, A., Oudeyer, P.Y., Gottlieb, J., 2015. Eye movements reveal epistemic curiosity in human observers. *Vis. Res.* 117, 81–90.
- Benureau, F.C.Y., Oudeyer, P.-Y., 2016. Behavioral diversity generation in autonomous exploration through reuse of past experience. *Front. Robot. AI* 3, 8. <http://dx.doi.org/10.3389/frobt.2016.00008>.
- Clement, B., Roy, D., Oudeyer, P.-Y., Lopes, M., 2015. Multi-armed bandits for intelligent tutoring systems. *J. Educ. Data Mining* 7 (2), 20–48.
- Forestier S, Oudeyer P-Y. 2016 Modular Active Curiosity-Driven Discovery of Tool Use. 2016 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS).
- Gottlieb, J., Oudeyer, P.-Y., Lopes, M., Baranes, A., 2013. Information seeking, curiosity and attention: computational and neural mechanisms. *Trends Cogn. Sci.* 17 (11), 585–596.
- Kaplan, F., Oudeyer, P.-Y., 2003. Motivational principles for visual know-how development. In: Prince, C.G., Berthouze, L., Kozima, H., Bullock, D., Stojanov, G., Balkenius, C. (Eds.), *Proceedings of the 3rd International Workshop on Epigenetic Robotics: Modeling Cognitive Development in Robotic Systems*, vol. 101. Lund University Cognitive Studies, Lund, pp. 73–80.
- Kaplan, F., Oudeyer, P.-Y., 2007b. In search of the neural circuits of intrinsic motivation. *Front. Neurosci.* 1 (1), 225–236.

- Lopes, M., Oudeyer, P.Y., 2012. The strategic student approach for life-long exploration and learning. In: IEEE International Conference on Development and Learning and Epigenetic Robotics (ICDL). IEEE, pp. 1–8.
- Lopes, M., Lang, T., Toussaint, M., Oudeyer, P.-Y., 2012. Exploration in Model-Based Reinforcement Learning by Empirically Estimating Learning Progress. In: Proceedings of Neural Information Processing Systems (NIPS 2012). NIPS, Tahoe, USA.
- Moulin-Frier, C., Nguyen, M., Oudeyer, P.-Y., 2014. Self-organization of early vocal development in infants and machines: the role of intrinsic motivation. *Front. Cogn. Sci.* 4, 1–20.
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